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Question Paper Code: 42452

B.E./B.Tech. DEGREE EXAMINATION, APRIL/MAY 2018 Fifth Semester

Electronics and Communication Engineering EC 2304 – MICROPROCESSORS AND MICROCONTROLLERS (Regulations 2008)

(Common to PTEC 2304 – Microprocessors and Microcontrollers for B.E. (Part-Time) Fifth Semester – ECE – Regulations 2009)

Time: Three Hours Maximum: 100 Marks

Answer ALL questions

PART – A

- 1. Define Microprocessor.
- 2. List the steps involved in the instruction execution.
- 3. What are assembler directives? Give two examples.
- 4. List the instructions provided by 8086 for ASCII arithmetic.
- 5. State the importance of sample and hold circuit.
- 6. List the applications of programmable interval timer.
- 7. List the jump statements of 8086.
- 8. Write a program to find the 2's complement using 8051.
- 9. What is meant by RTC?
- 10. State the importance of relay coils.

PART - B

 $(5\times16=80 \text{ Marks})$

11. a) With a neat diagram, explain the Bus Interface Unit and Execution Unit of 8086 microprocessor.

b) Explain the maximum mode configuration of 8086 with a neat diagram. Mention the functions of various signals.



12. a) Discuss on the various classifications of 8086 microprocessor instructions with appropriate examples.

(OR)

- b) Write the algorithm to sort an array of 10 bytes in ascending order. Also write an 8086 ALP for the algorithm.
- 13. a) Explain the programming and operating modes of 8255 PPI in detail.

(OR)

- b) With neat block diagram, explain the 8279 keyboard and display controller.
- 14. a) Explain the architecture of 8051 microcontroller with neat diagram.

(OR)

- b) i) Discuss on the various addressing modes of 8051 with appropriate examples. (10)
 - ii) Discuss on the various interrupt sources available in 8051.
- 15. a) With neat sketch, explain the design of traffic light controller using microcontroller and microprocessor.

(OR)

b) Draw the diagram to interface a stepper motor with microcontroller/microprocessor and write an ALP to run the stepper motor in both forward and reverse direction with delay.

State the importance of sample and bold of

PART-11